



DAN Experiment Onboard the Curiosity Rover: Modelling of the Neutron Sensors Response

V. Shvetsov, FLNP JINR

ISINN-26, May 28 - June 1, 2018, Xi'an, China

31.05.2018



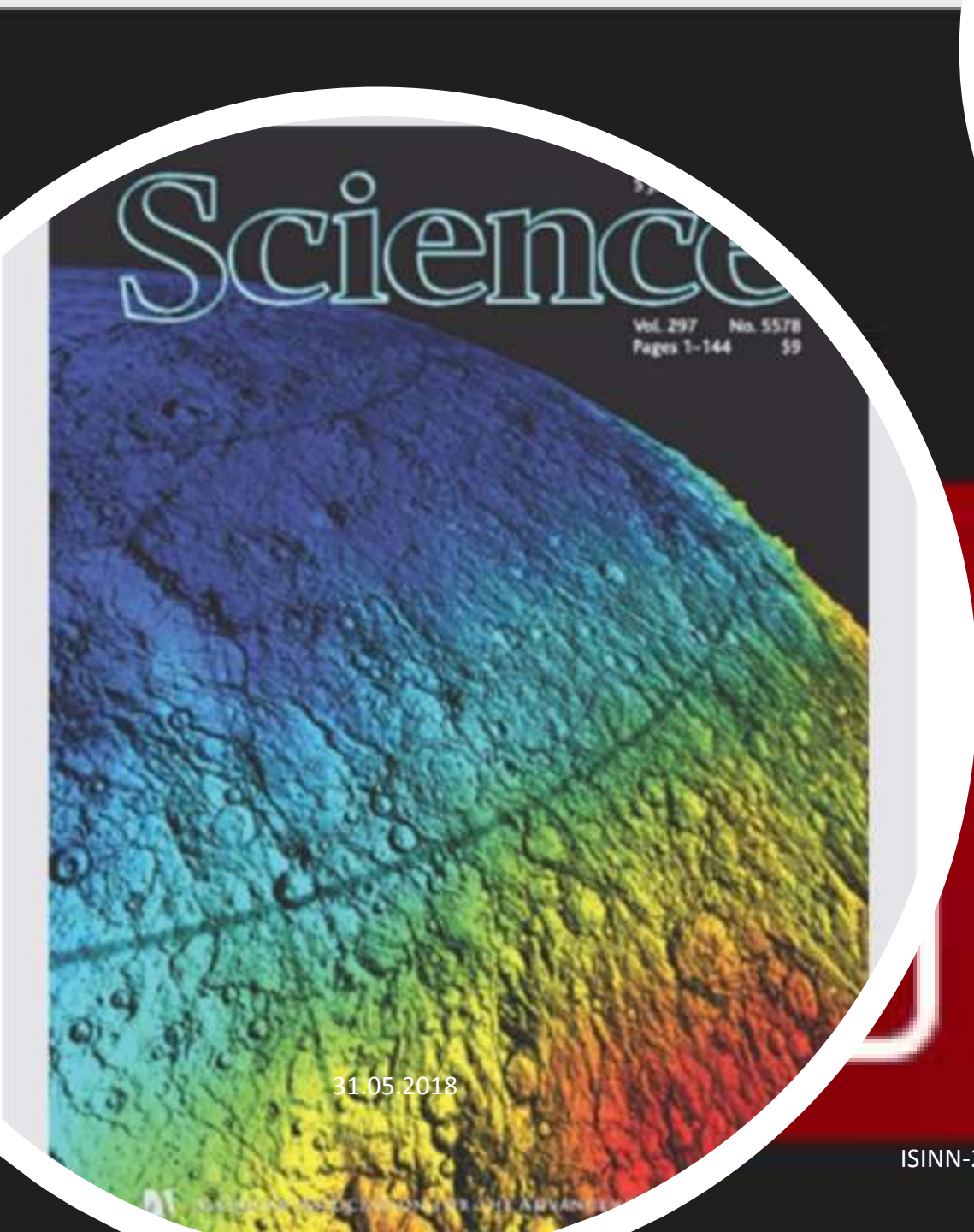
Overview

- Introduction;
- DAN experiment history;
- Martian Soil Modelling Stand at JINR;
- Experiments and Comparison with Martian Data;

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Topics

- Jobs are updated 24/7
- **Water on Mars Confirmation from Mars Odyssey Mission**
Science 05 Jul 2002:
Vol. 297, Issue 5578, pp. 78-81
DOI: 10.1126/science.1073616
- Get job alerts for new c

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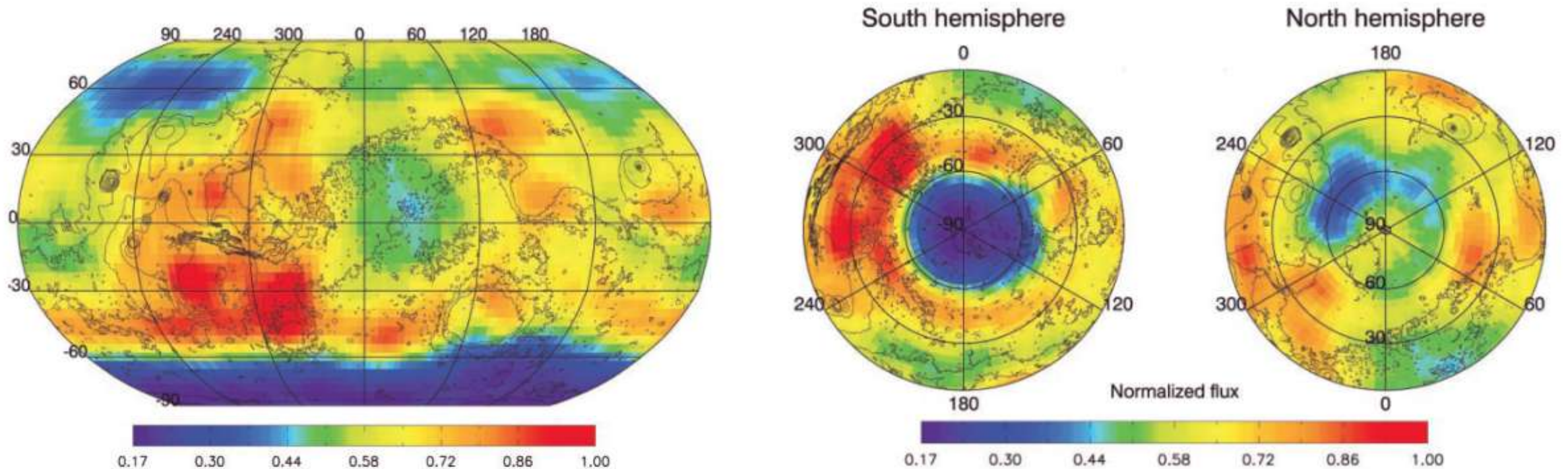
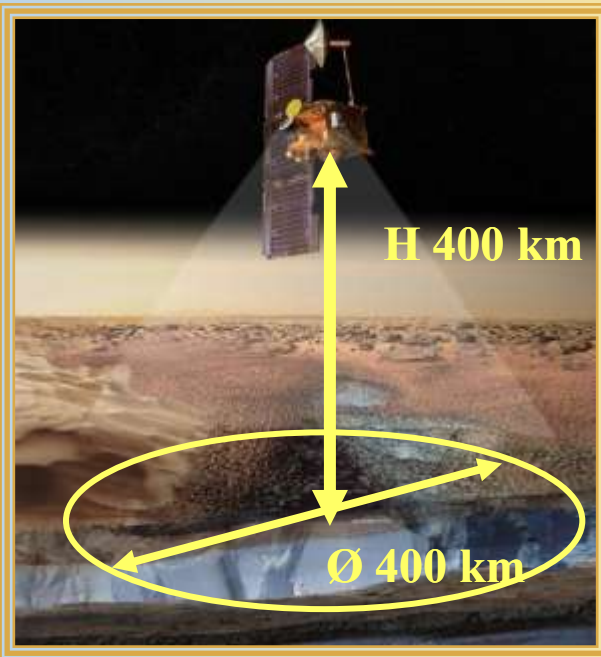


Fig. 1. The initial map of orbital measurements of martian epithermal neutrons by HEND with energies at 0.4 eV to 100 keV for the first 55 days of mapping. Pixels with sizes $4^\circ \times 4^\circ$ are smoothed with the scale of 10° . The size of 4° at the equator corresponds to a linear scale of about 240 km. The contours of MOLA topography (12) are shown for comparison. The map is normalized to 1 at the pixel with the highest count rate, 0.26 counts/s in Solis Planum (270°E , 30°S). The minimal statistical significance of any pixel is above 5σ of background fluctuations; minimal time exposure for pixels is 600 s.

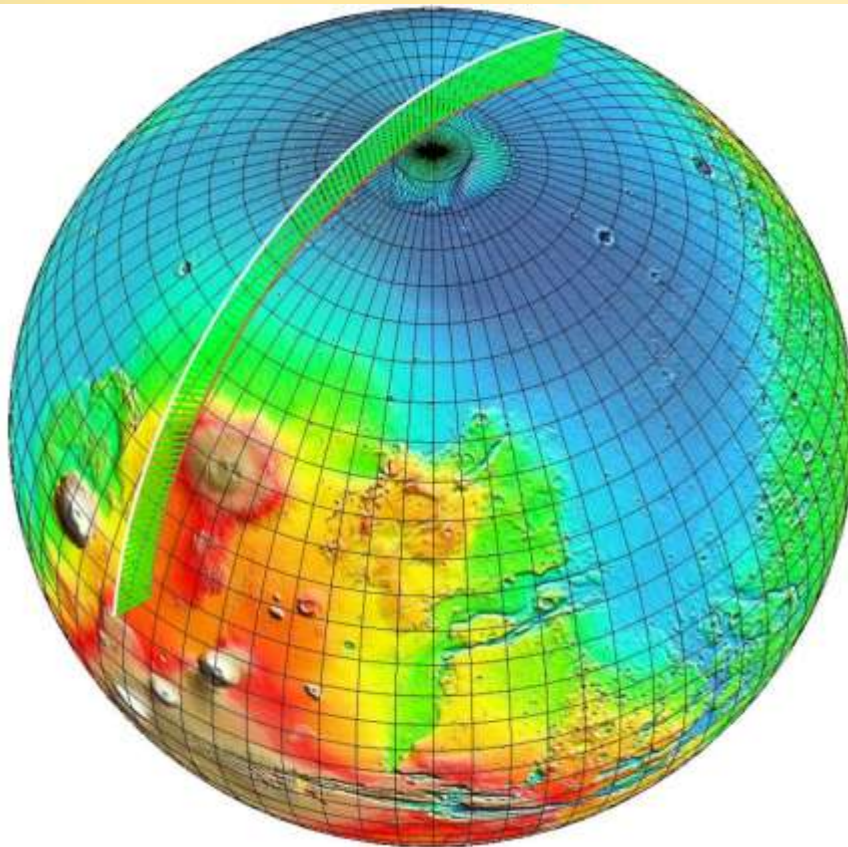
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Building the Map

On the surface of planet making a mesh with selected size of pixels. In each pixel independently accumulating counts and exposure time. Selecting a time interval, detector and set of channels to create map.



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Main parameters of orbit:

Altitude – 400 km;
Orbital period – 2 hours;
Orbit inclination – 93.1°

Poor spatial resolution.
Pixel size is about 400 km.
Should be about 10-50 km to choose proper place for lander/rover mission



We need neutron detector with collimator on the orbiter



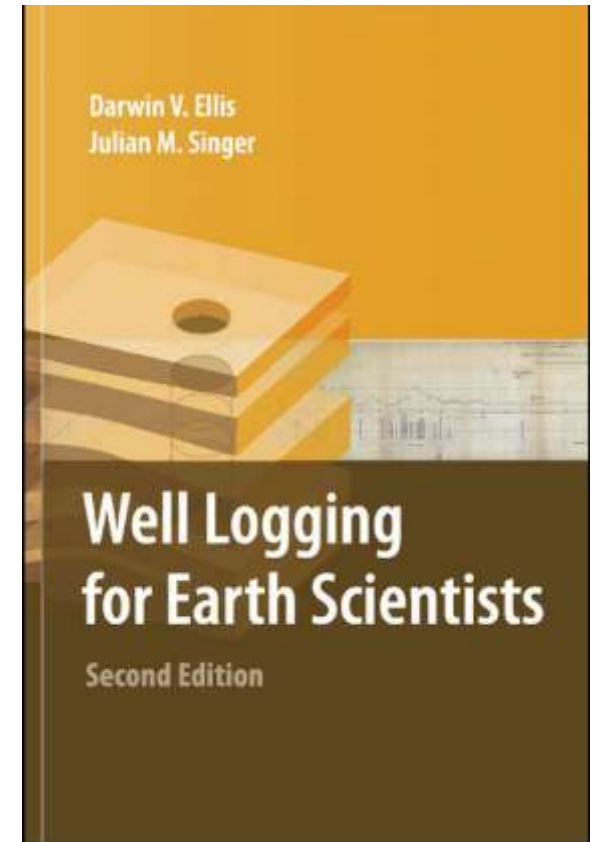
With collimated orbital detector we can choose proper place for landing. Now we need an instrument onboard the rover to seek for water ice under the wheels



Neutron logging

PONTECORVO, B., "Neutron Well Logging," *Oil and Gas Journal*, p. 32, September 11, 1941.

Flerov, G. N., and Alexeyev, F. A. The use of radioactive radiations in prospecting and developing oil deposits in the USSR: World Petroleum Cong., 4th sess., Rome, Proc. sec. 1, p. 737-746, 1955.



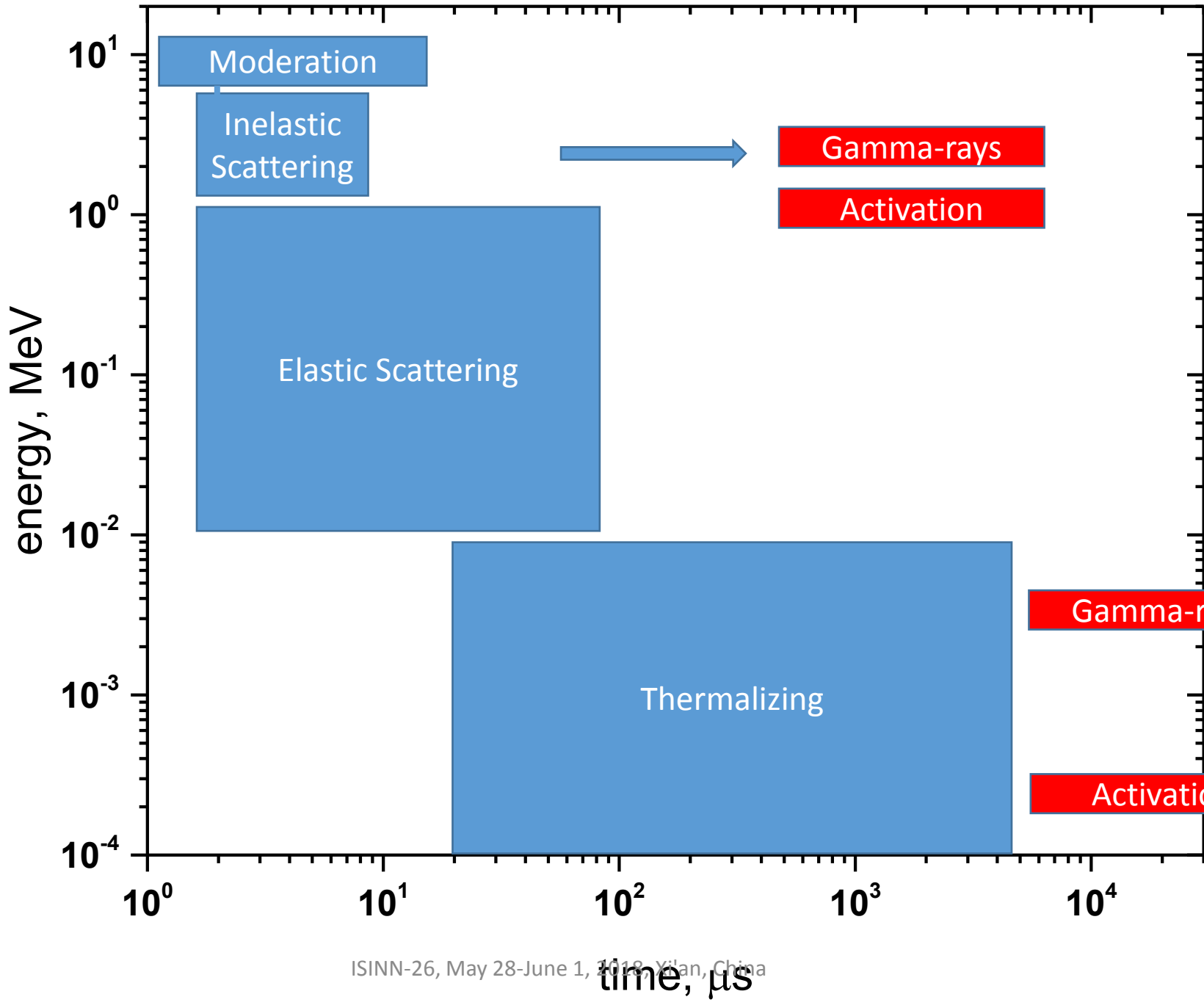
Neutron Logging

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2005 -2006: Testing DAN laboratory prototype



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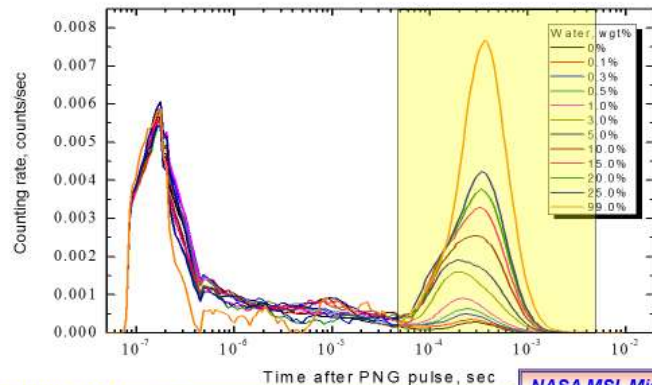
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Numerical Modeling: Counting rate in case of active regime

Thermal neutrons counting rate obtained as difference between counting rate detected by CTN and CETN
 Selection of time interval for analyzes of water amount in soil.



Physical measurements for DAN FU01 calibrations



DAN Science Team

Name	Institution	Role in the team
Игорь МИТРОФАНОВ / Igor MITROFANOV (PI)	Институт космических исследований РАН / IKI	Principal Investigator
Максим ЛИТВАК / Maxim LITVAK (DPI and LS)	Институт космических исследований РАН / IKI	DAN leading scientist, physical analysis of DAN data for neutron activation
Антон САНИН / Anton SANIN (Co-I)	Институт космических исследований РАН / IKI	DAN project manager, instrument numerical calibrations
Александр КОЗЫРЕВ / Alexander KOZYREV (Co-I)	Институт космических исследований РАН / IKI	Monitoring and validation of DAN physical performance
Валерий ШВЕЦОВ / Valery SHVETSOV (Co-I)	Объединенный институт ядерных исследований / JINR	DAN physical calibration facilities
Руслан КУЗМИН / Ruslan KUZMIN (Co-I)	ГЕОХИ РАН / Vernadsky Institute	DAN representative in MSL landing site selection process
Давид ГИЛИЧИНСКИЙ / David GILICHINSKY (Co-I)	Институт почвоведения РАН / Institute of soil science	Field tests of DAN analogs, reference library for express data analysis
NASA-related Co-I #1	TBD	DAN express data analysis during operations
NASA-related Co-I #2	TBD	Inter-instrument DAN scientist
NASA-related Co-I #3	TBD	Fast numerical modeling for express data analysis
NASA-related Co-I #4	TBD	Development and delivery of DAN PDS data

2004 - 2008





DAN: Instrument Delivery Review

DAN/DE FM-1 characteristics

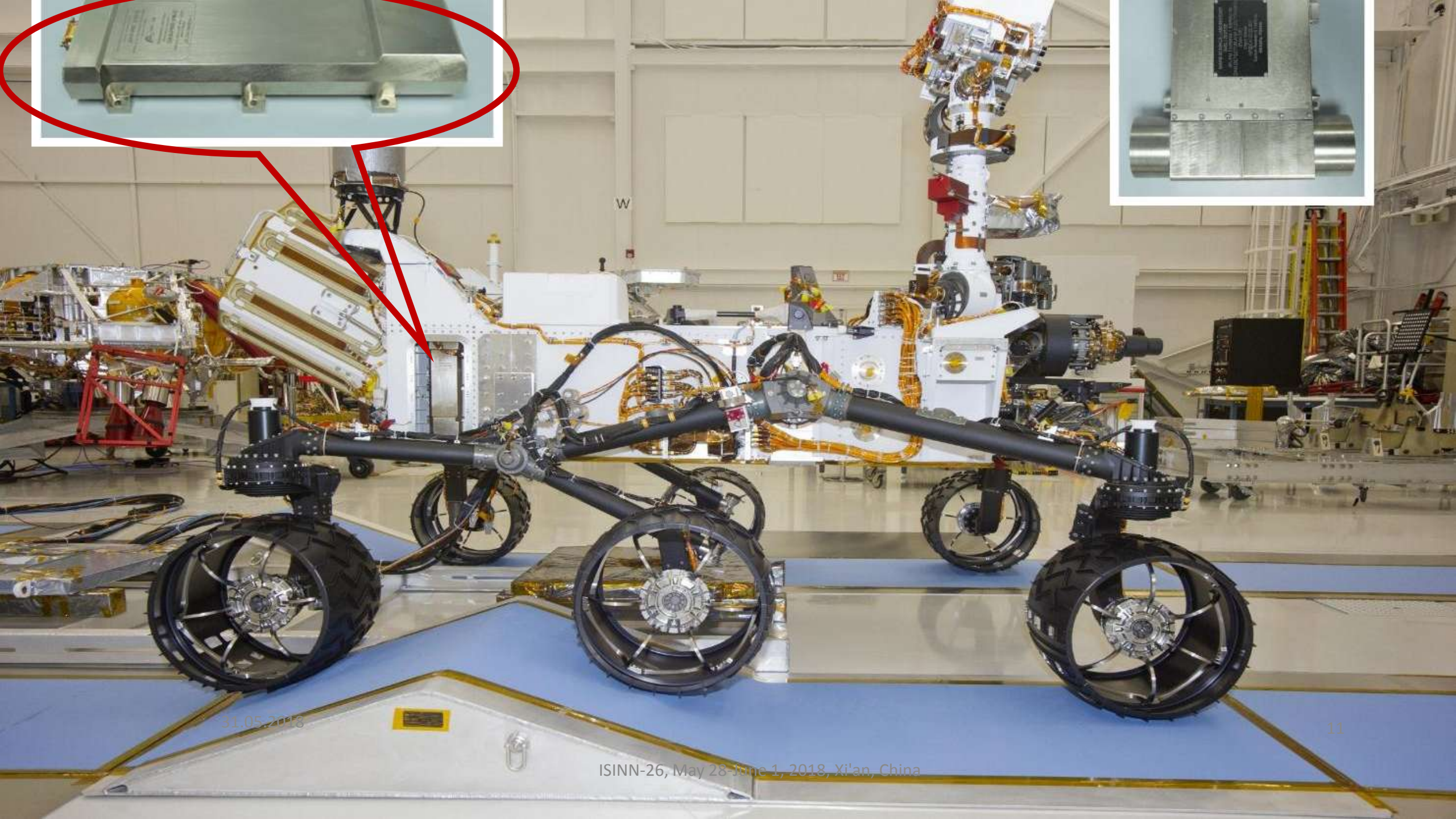
TABLE 1. The main DAN characteristics

Parameter	Value
Max Dimensions	204 x 61 x 211 mm
Mass	1.88 kg
Number of detectors	2 (CTN and CETN)
Neutron energy (detected neutrons)	<0.1 MeV (CTN detector) 0.4 eV – 0.1 MeV (CETN detector)
Number of spectra channels per each detector	16 (linear)
Time scale per each detector	64 (logarithmic)
Duration of Lowest time bin	2 μ s
Spatial resolution	<1 m
Max Power in passive mode	< 4.1 W
Max Power at standby mode	< 3.0 W
Warranty	5 years
Operation temperature range	[-40, + 50] °C
Survival temperatures	[- 55, + 70] °C
Input Voltage range (Normal operations)	22 -36 V
31.05.2018 Input Voltage range (Surviving)	0 – 40 V
Readiness to operate after switching power on	< 1 sec



FM-1





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7:02 a.m. PST, Nov. 26,
2011

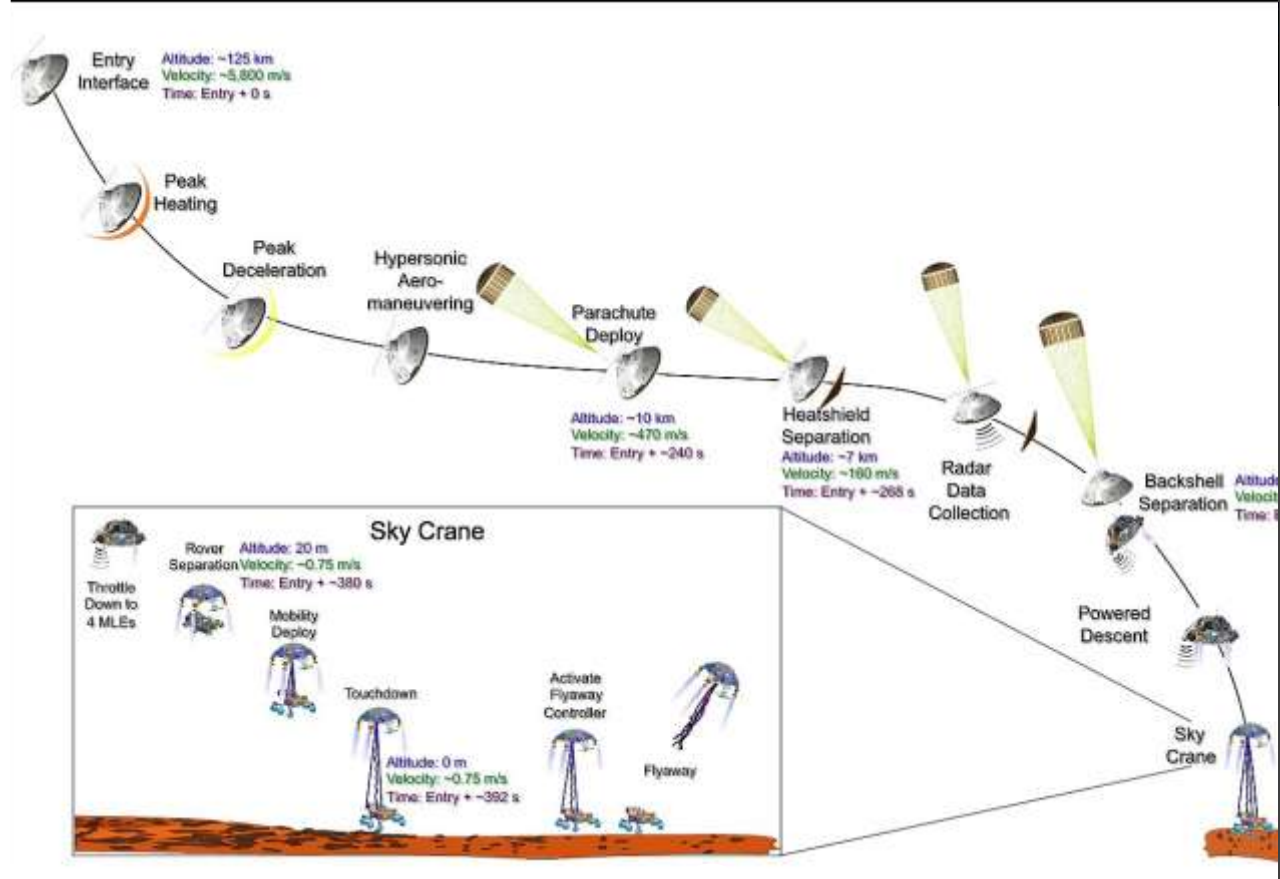
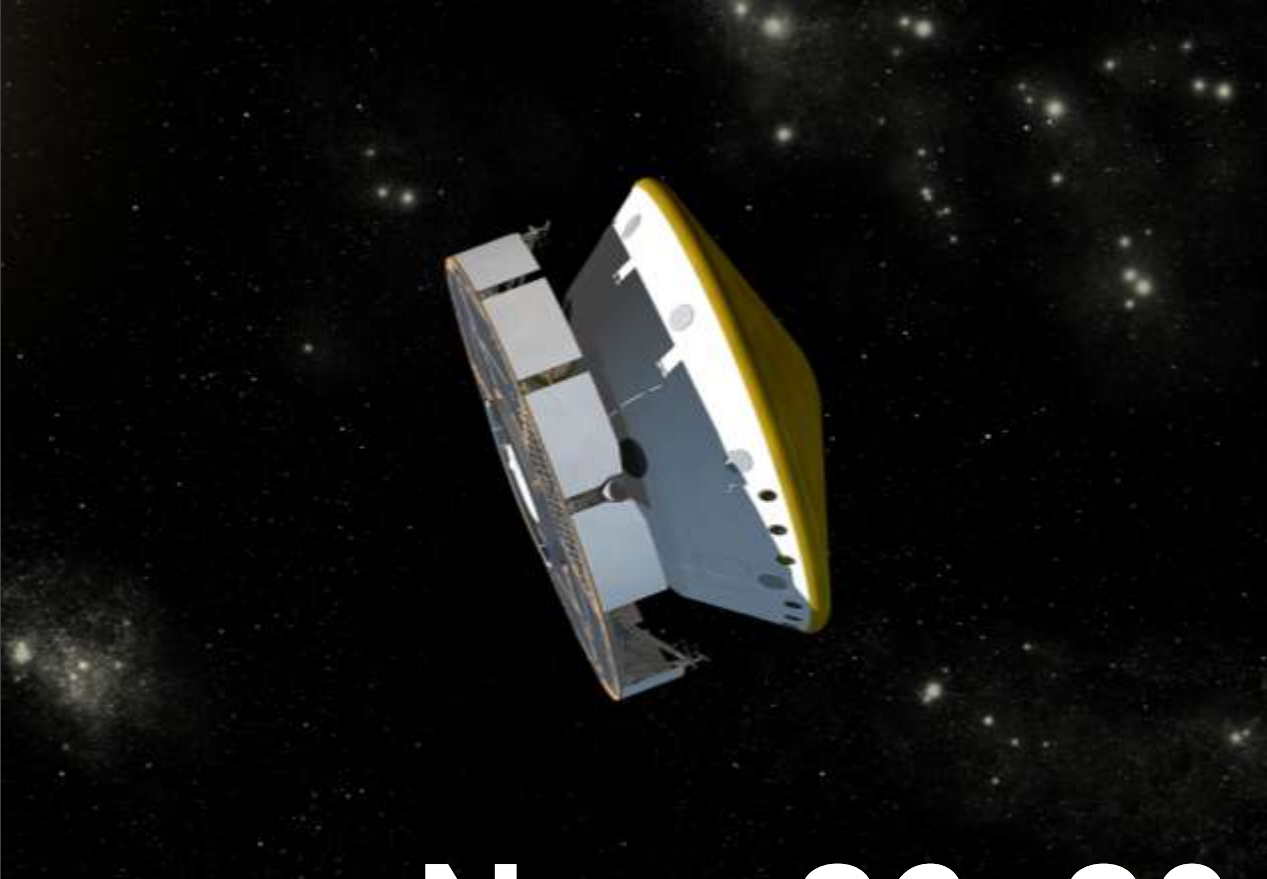
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Nov. 26, 2011 - Aug. 6, 2012



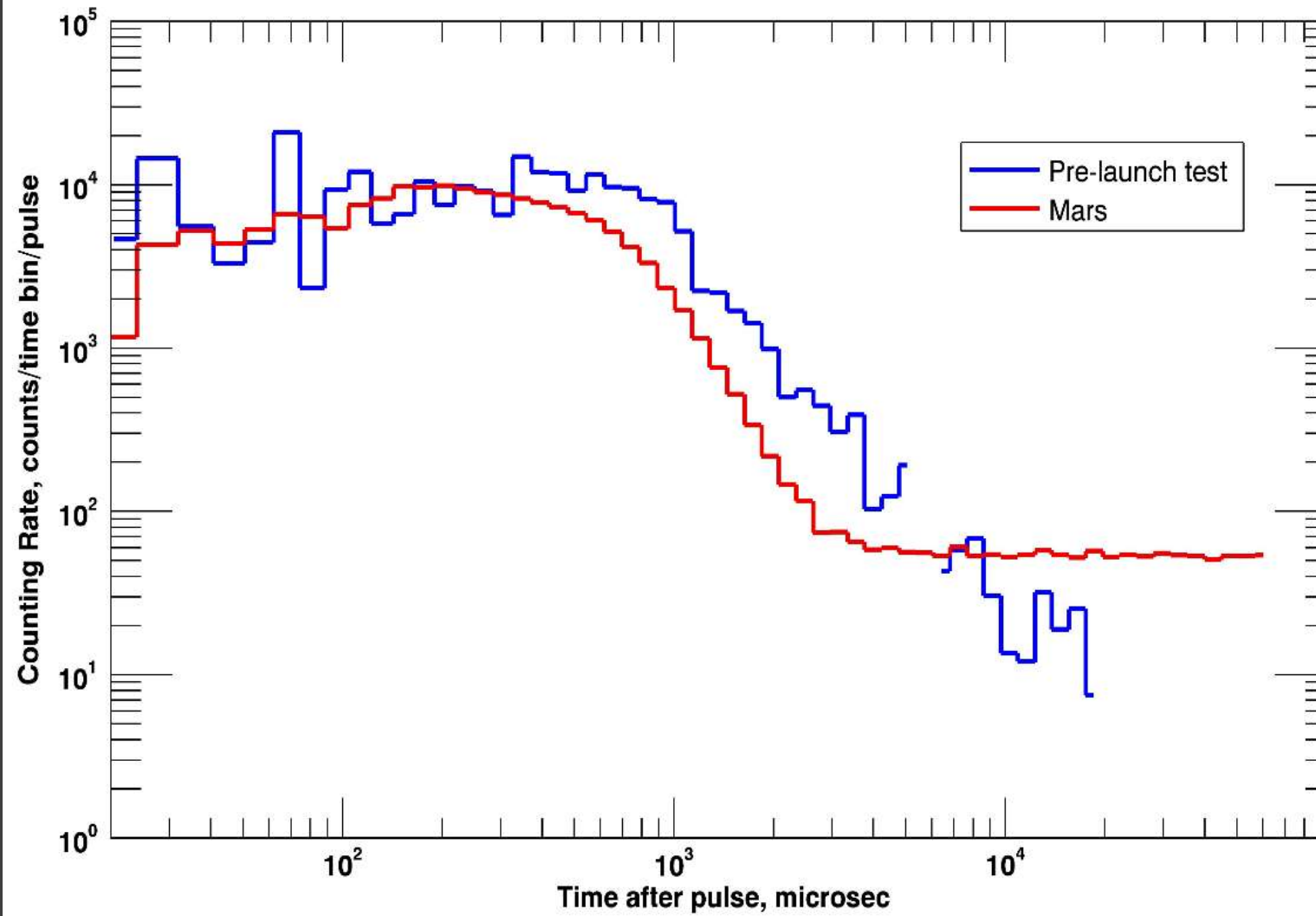
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Aug. 2012, Mars, Gale Crater

ISINN-16 (May 2018) (no. 1791), Xi'an, China

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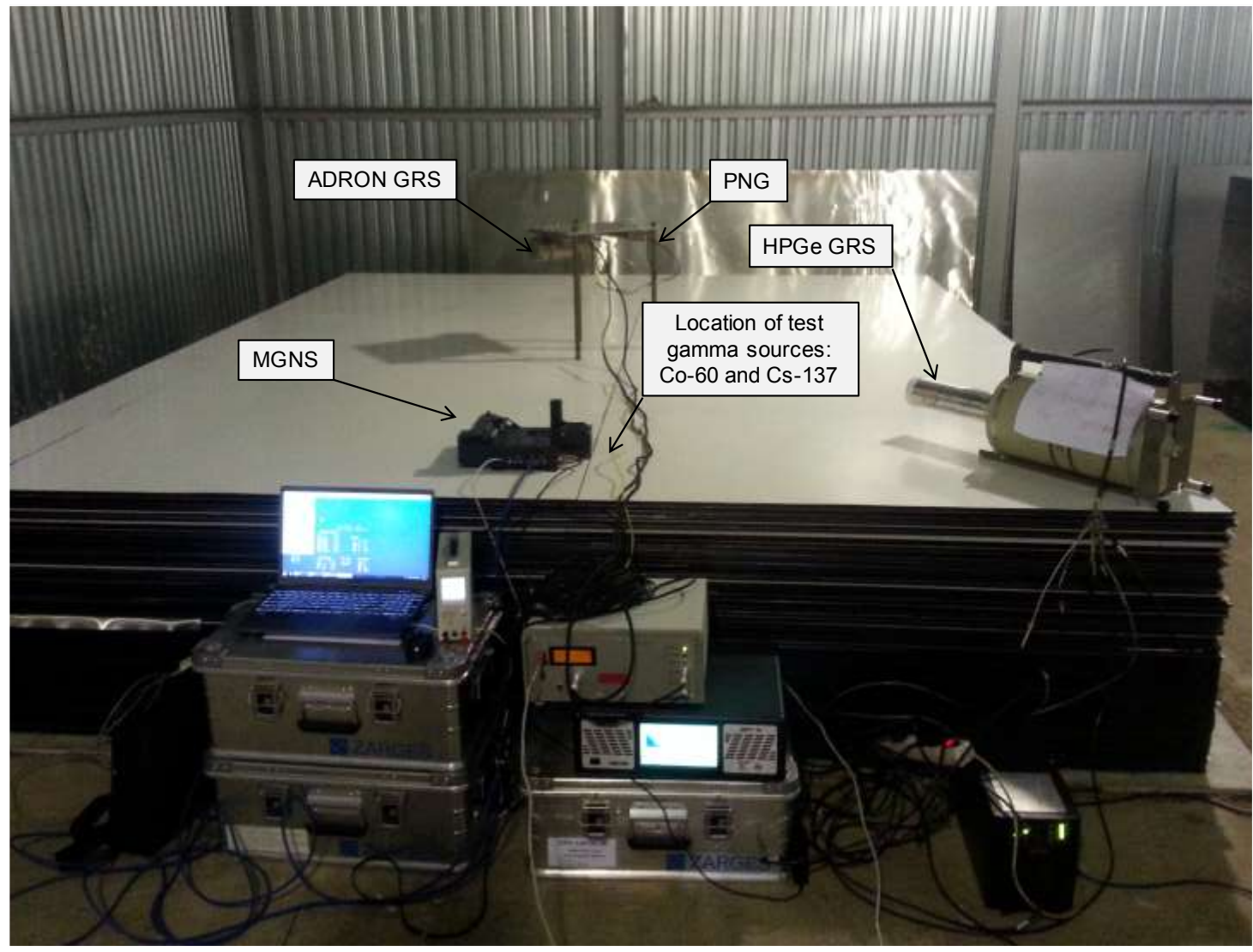
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Table 1
Element: the tests

Element Oxide

SiO₂
Na₂O
MgO
Al₂O₃
K₂O
CaO
Fe₂O₃
Sr^b
Ba^b
Zr^b

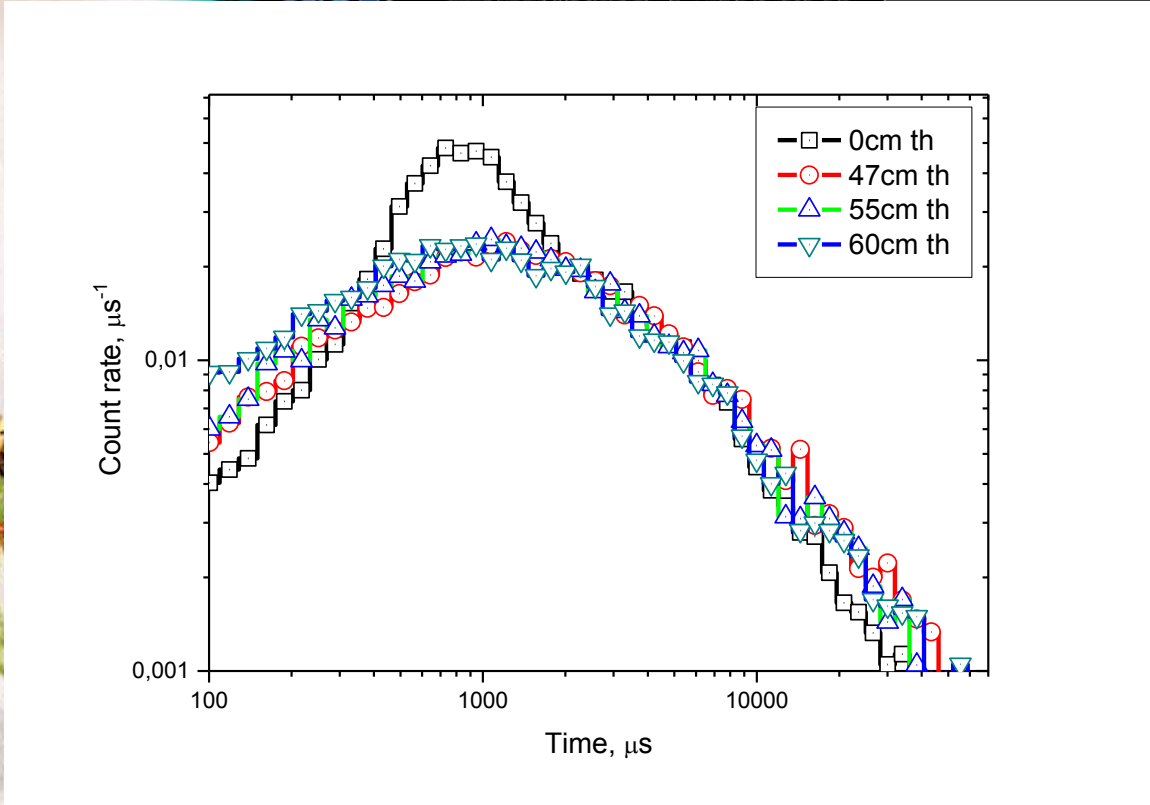
Material	Layer thickness, mm
PVC	0,7
Al	1
Glass	10
Fe	1
Glass	10
Al	1
Glass	10
PVC	0,7
Fe	1
Glass	10
Al	1
Glass	10
PVC	0,7
Fe	1
Glass	10
Al	1
Glass	10
Fe	1
Glass	10
PVC	0,7
Al	1
Glass	10
Fe	1
Glass	10
PVC	0,7
Al	1
Glass	10
Fe	1
Glass	10



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DAN FU2 at the Martian Soil Model

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DAN CTN and CETN Sensors Response Modelling

- Variation of the water ice content from the dry soil to 15% weight;
- Variation of the salinity from 0 to 500 g/l;
- Extracted parameters - die away constants;

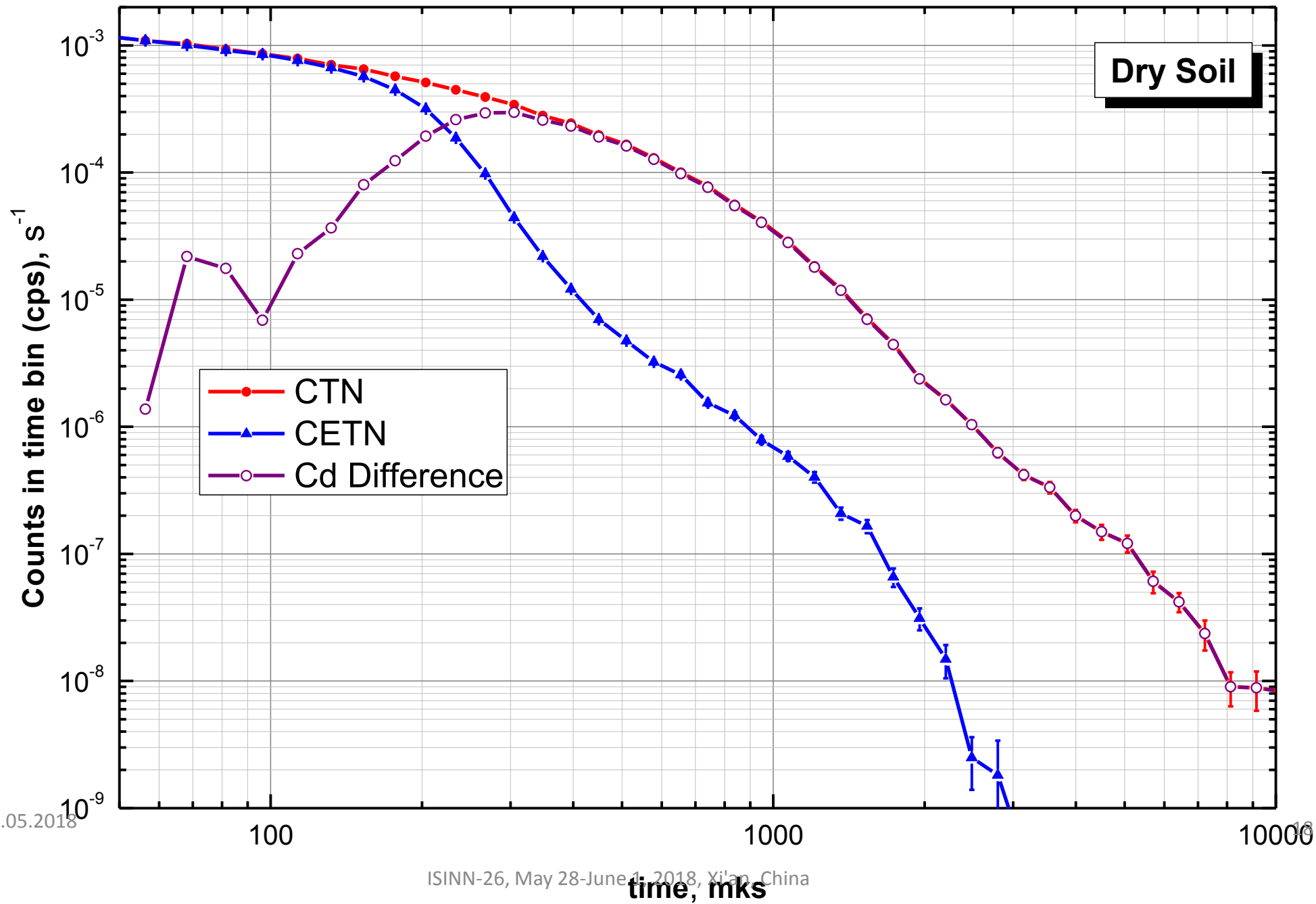
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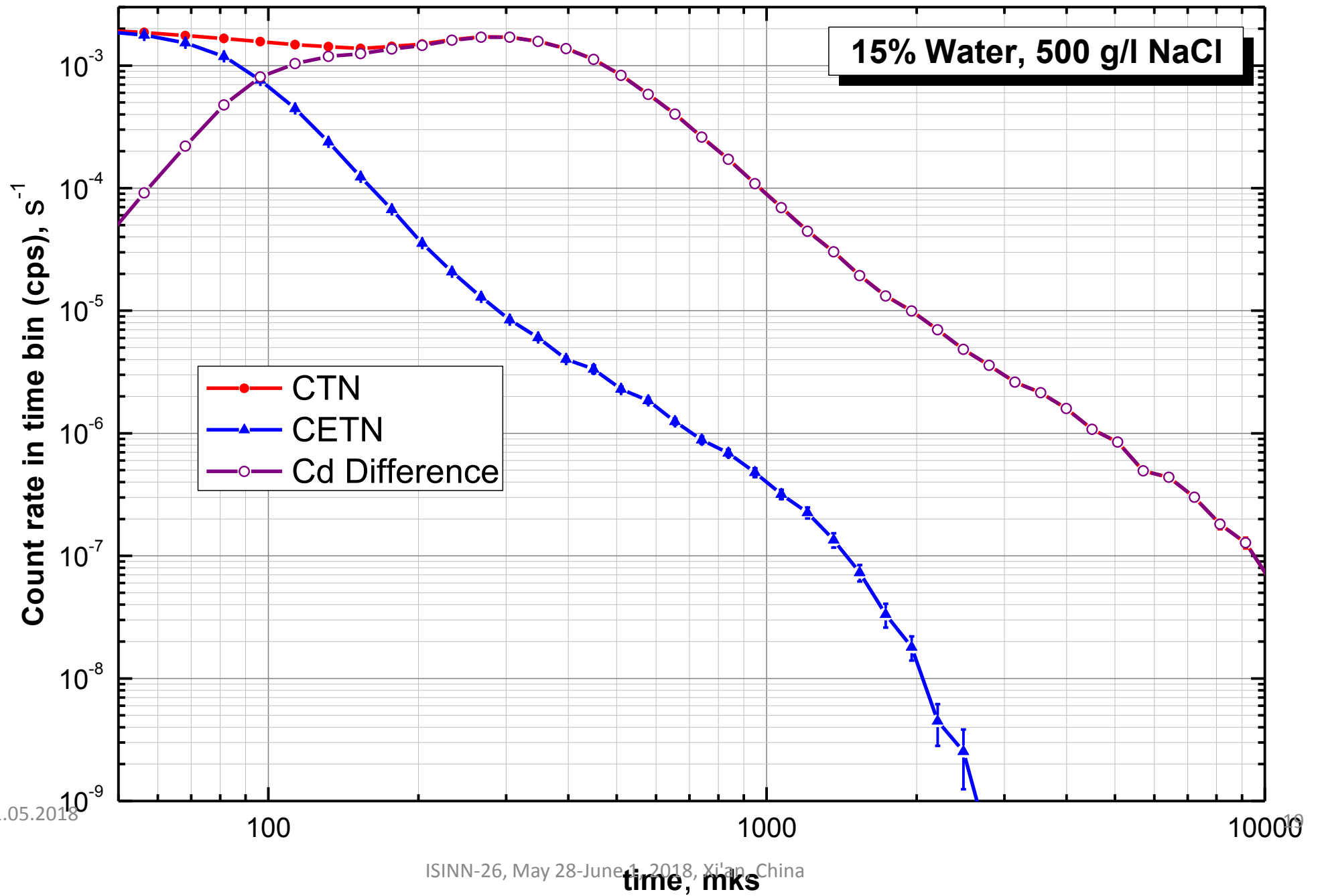


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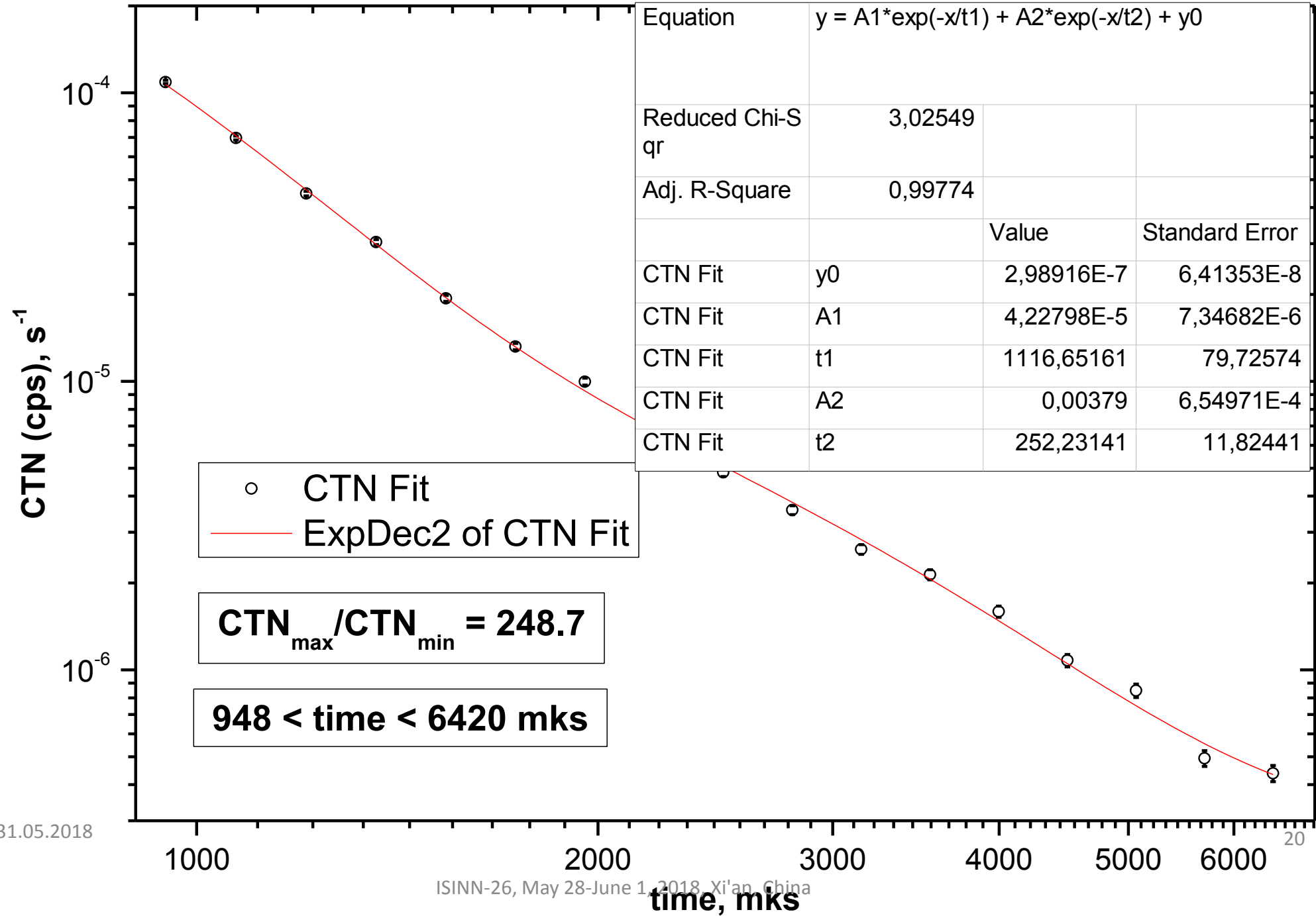


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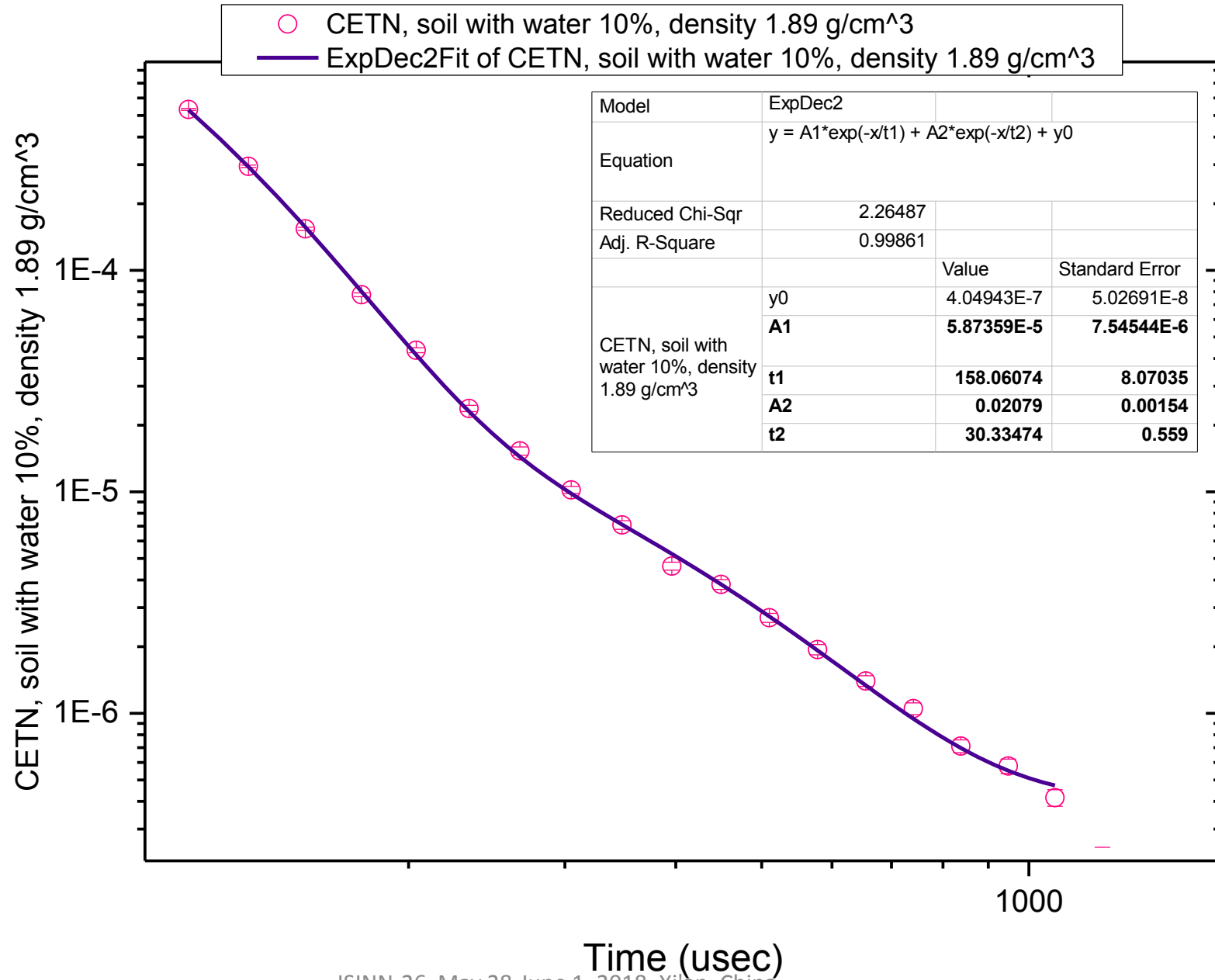




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time, mks

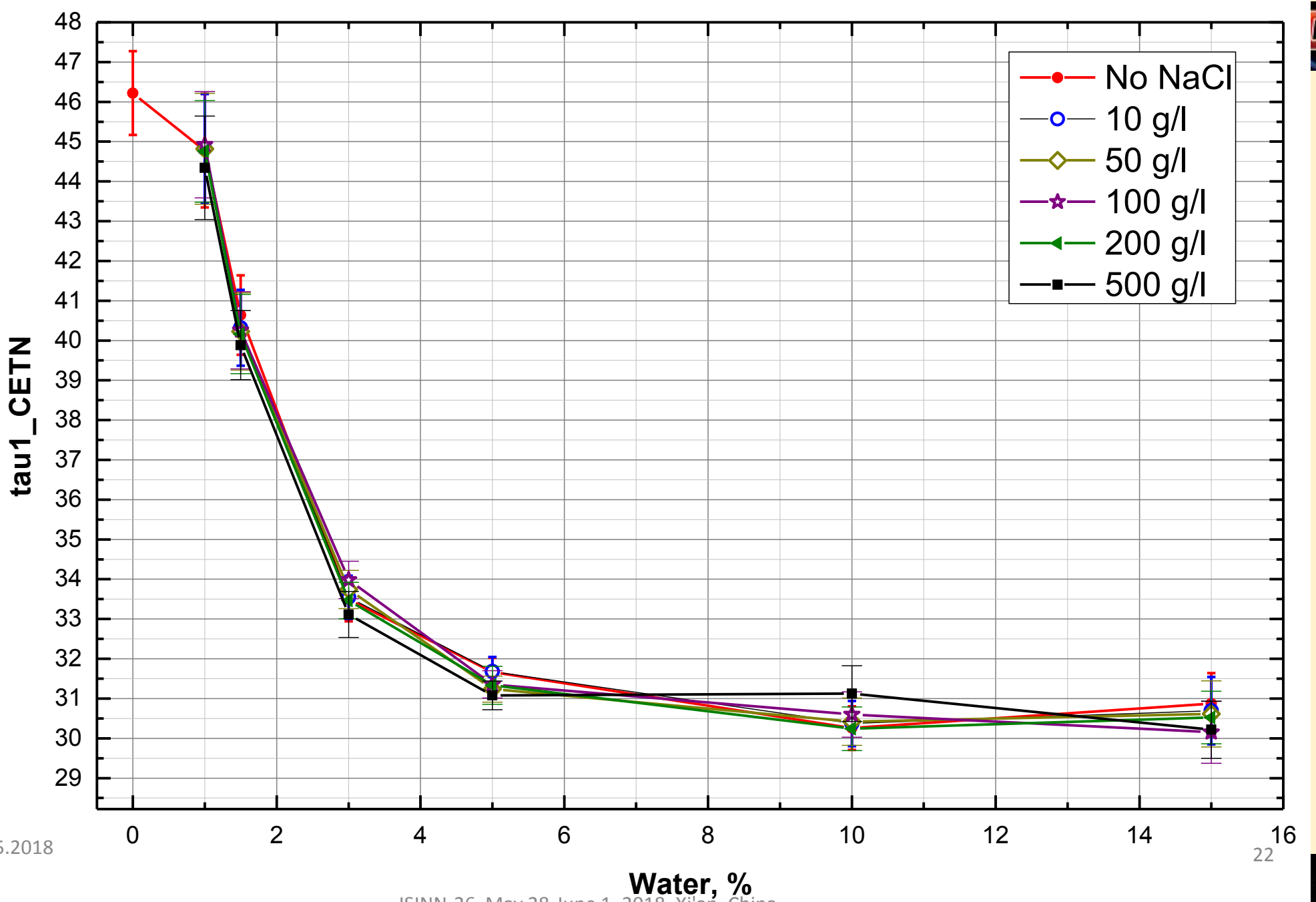


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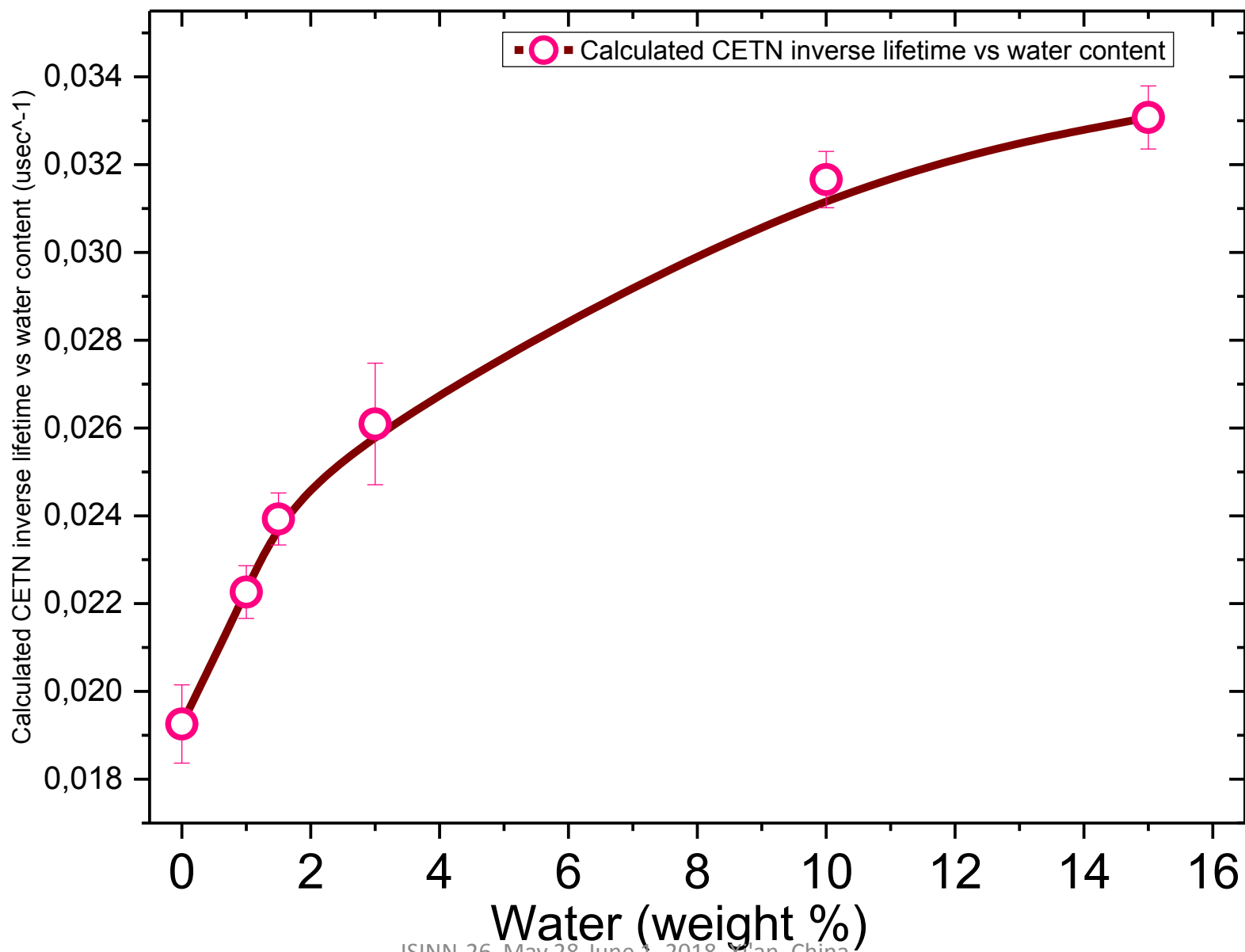


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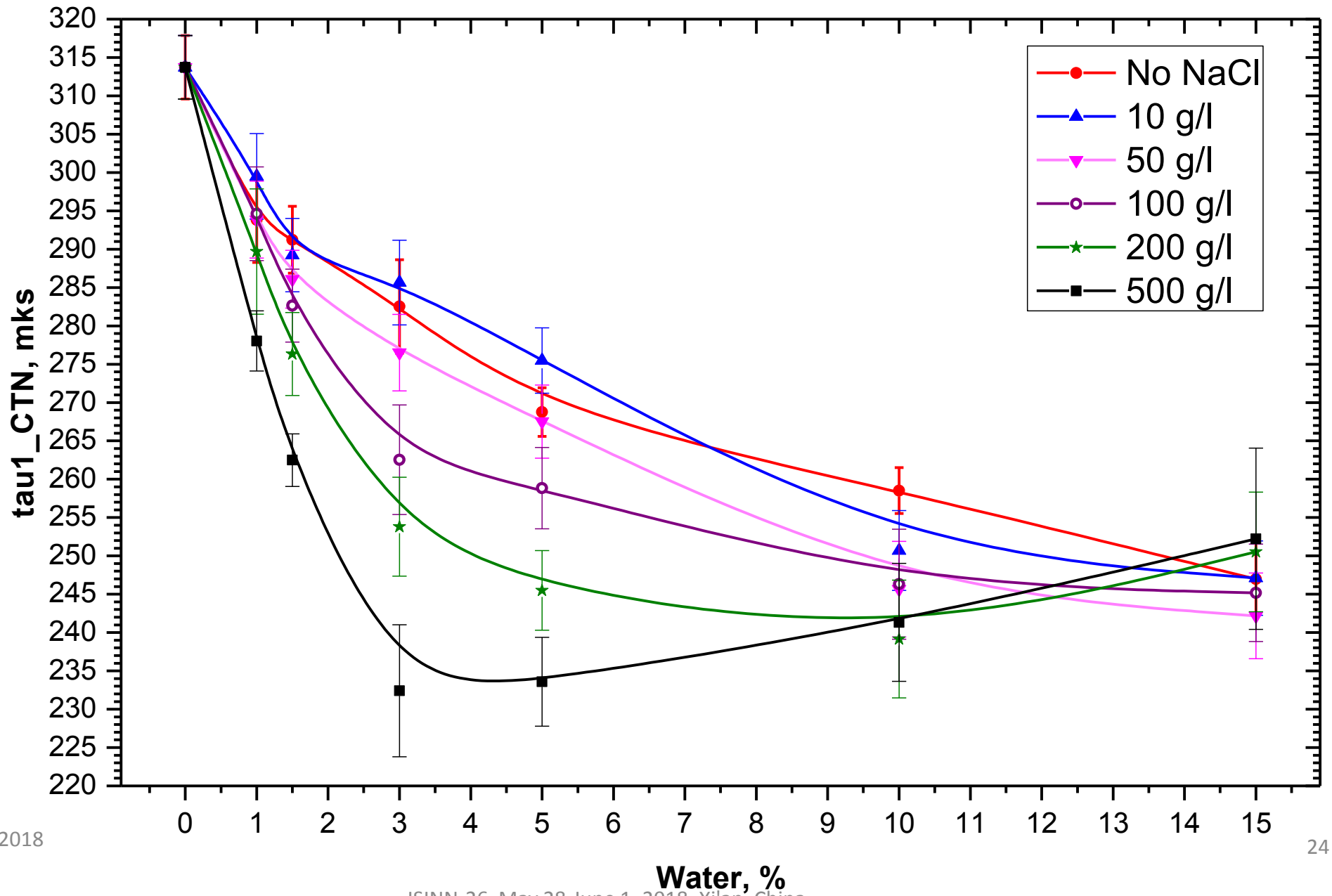
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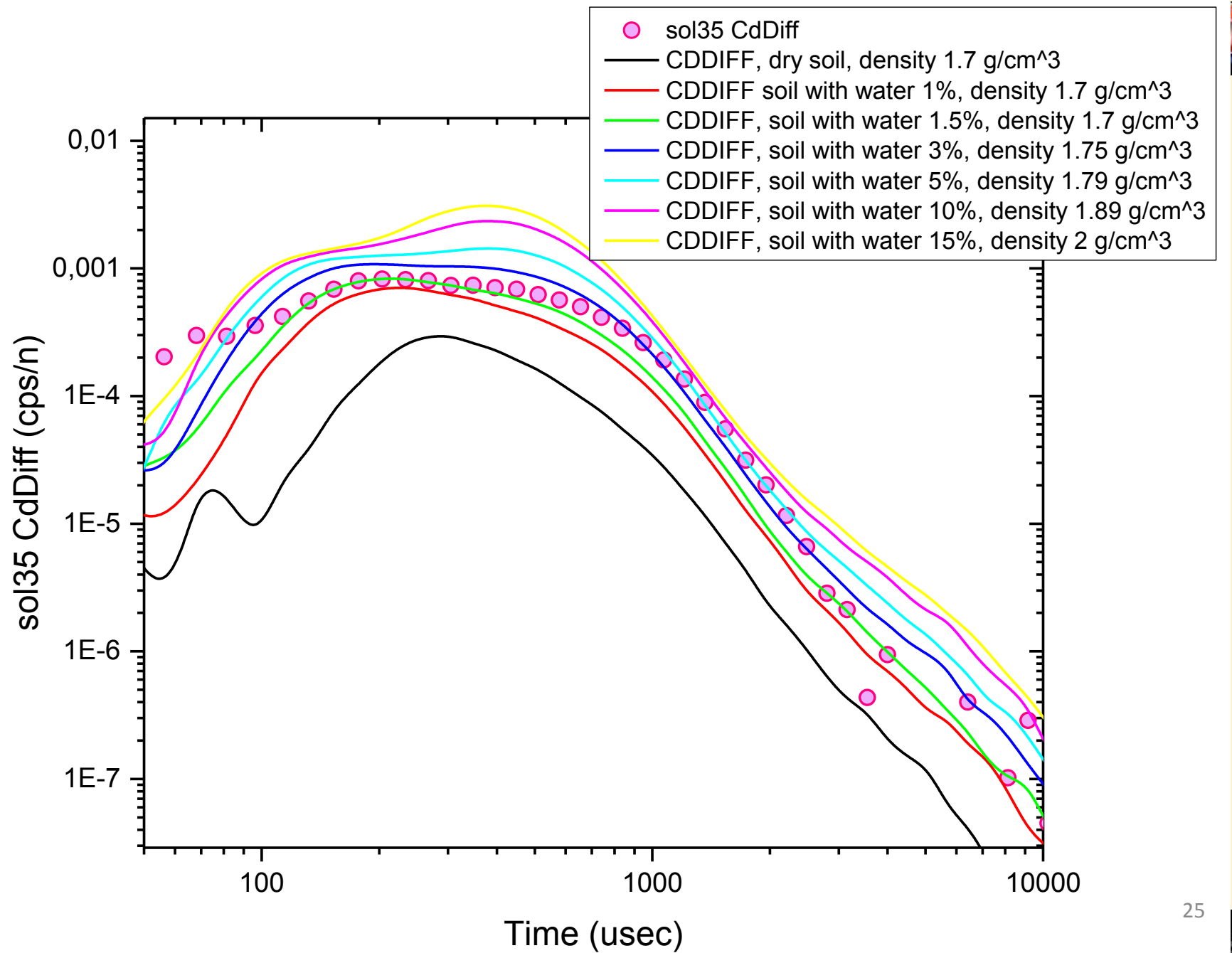


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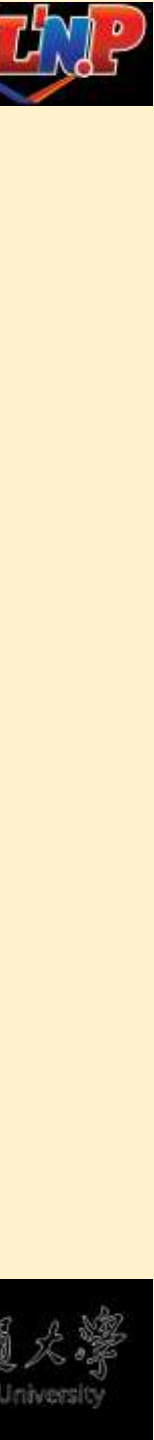
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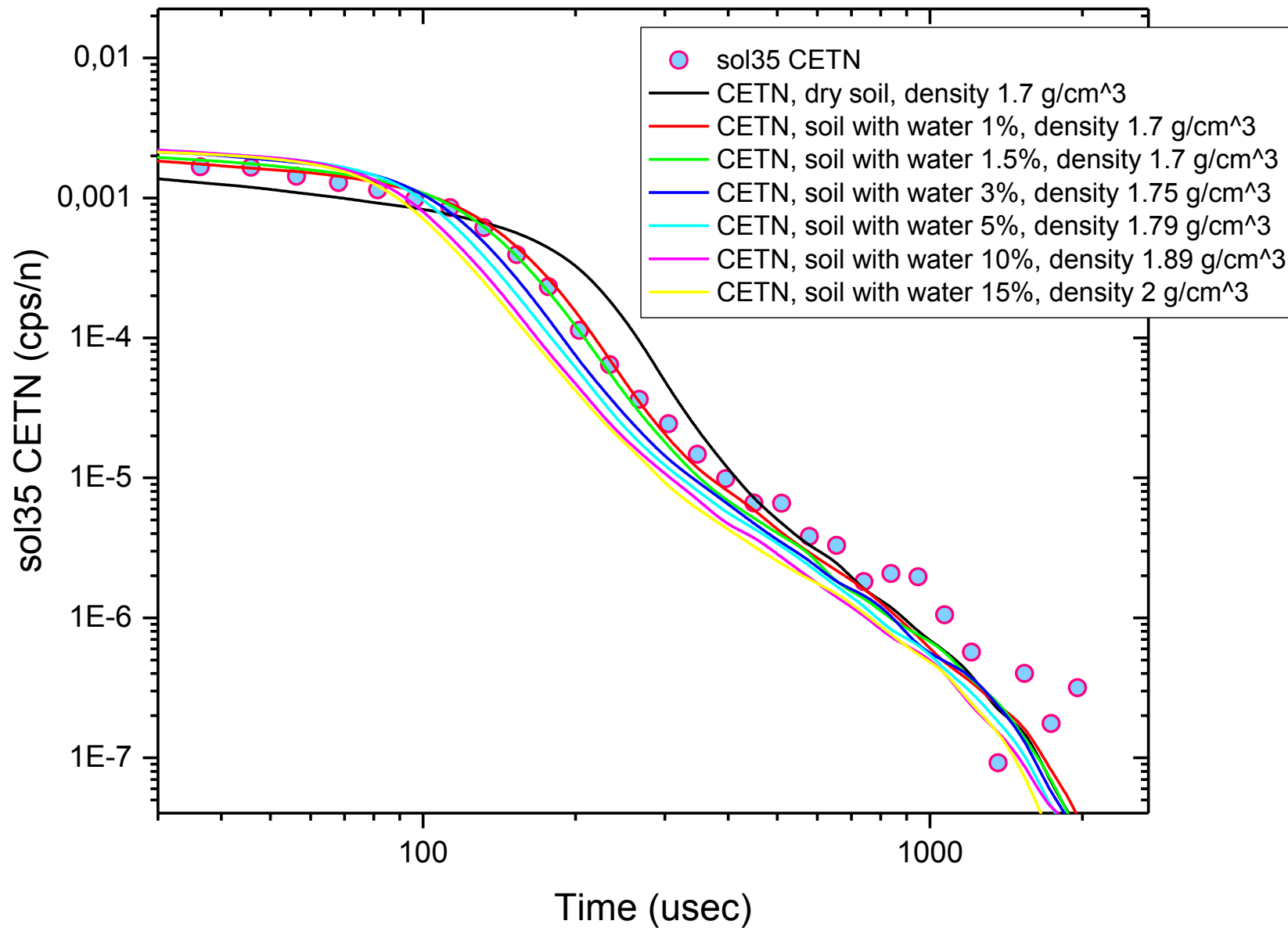
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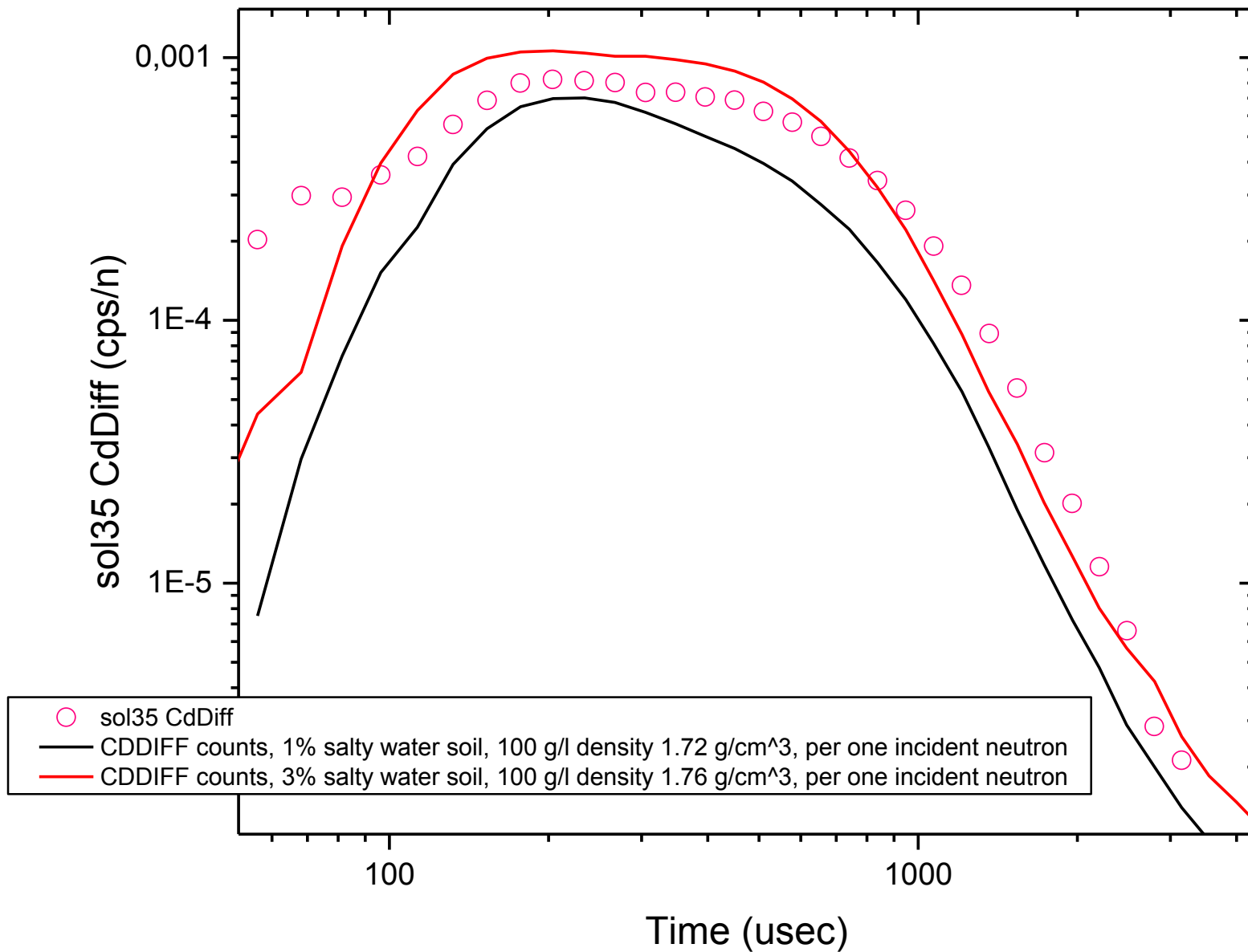


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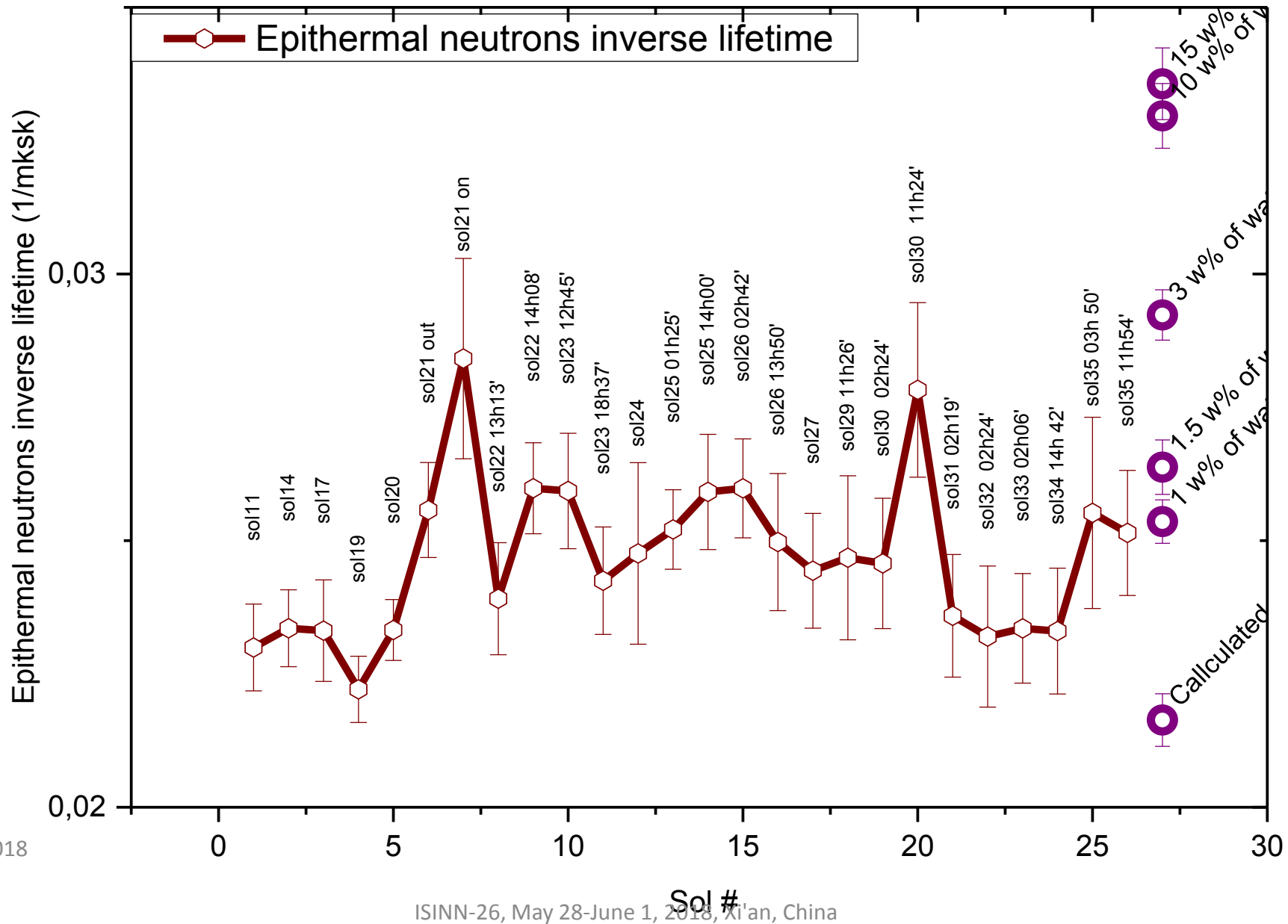


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Hydrogen Index (calc)



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